

Chapter 12

Tensors

So far, we have defined tangent vectors, cotangent vectors, and also vector fields and 1-forms. We will now define tensors. We will do this by starting with the example of a specific type of tensor.

- A (1, 2) **tensor** A_P at $P \in \mathcal{M}$ is a map

$$A_P : T_P \mathcal{M} \times T_P \mathcal{M} \times T_P^* \mathcal{M} \rightarrow \mathbb{R} \quad (12.1)$$

which is linear in every argument. \square

So given two vectors u_P, v_P and a covector ω_P ,

$$A_P : (u_P, v_P, \omega_P) \mapsto A_P(u_P, v_P; \omega_P) \in \mathbb{R}. \quad (12.2)$$

Suppose $\{e_a\}, \{\lambda^a\}$ are bases for $T_P \mathcal{M}, T_P^* \mathcal{M}$. Write

$$A_{ab}^c = A_P(e_a, e_b; \lambda^c). \quad (12.3)$$

Then for arbitrary vectors $u_P = u^a e_a, v_P = v^a e_a$, and covector $\omega_P = \omega_a \lambda^a$ we get using linearity of the tensor map,

$$\begin{aligned} A_P(u_P, v_P; \omega_P) &= A_P(u^a e_a, v^b e_b; \omega_c \lambda^c) \\ &= u^a v^b \omega_c A_{ab}^c. \end{aligned} \quad (12.4)$$

It is a matter of convention whether A as written above should be called a (1, 2) tensor or a (2, 1) tensor, and the convention varies between books. So it is best to specify the tensor by writing indices as there is no confusion about A_{ab}^c .

A tensor of type (p, q) can be defined in the same way,

$$A_P^{p,q} : \underbrace{T_P \mathcal{M} \times \cdots \times T_P \mathcal{M}}_{q \text{ times}} \times \underbrace{T_P^* \mathcal{M} \times \cdots \times T_P^* \mathcal{M}}_{p \text{ times}} \rightarrow \mathbb{R} \quad (12.5)$$

in such a way that the map is linear in every argument.

- Alternatively, A_p is an element of the **tensor product space**

$$A_p \in \underbrace{T_p\mathcal{M} \otimes \cdots \otimes T_p\mathcal{M}}_{p \text{ times}} \otimes \underbrace{T_p^*\mathcal{M} \otimes \cdots \otimes T_p^*\mathcal{M}}_{q \text{ times}} \quad (12.6)$$

We can define the components of this tensor in the same way that we did for the (1, 2) tensor. Then a (p, q) tensor has components which can be written as

$$A_{b_1 \cdots b_q}^{a_1 \cdots a_p}.$$

- Some special types of (p, q) tensors have special names. A (1, 0) tensor is a linear map $A_p : T_p^*\mathcal{M} \rightarrow \mathbb{R}$, so it is a tangent vector. A (0, 1) tensor is a cotangent vector. A $(p, 0)$ tensor has components with p upper indices. It is called a **contravariant p -tensor**. A $(0, q)$ tensor has components with q lower indices. It is called a **covariant q -tensor**. \square

It is possible to add tensors of the same type, but not of different types,

$$A_{b_1 \cdots b_q}^{a_1 \cdots a_p} + B_{b_1 \cdots b_q}^{a_1 \cdots a_p} = (A + B)_{b_1 \cdots b_q}^{a_1 \cdots a_p}. \quad (12.7)$$

- A **tensor field** is a rule giving a tensor at each point. \square

We can now define the Lie derivative of a tensor field by using Leibniz rule in a chart. Let us first consider the components of a tensor field in a chart. For a (1, 2) tensor field A , the components in a chart are

$$A_{ij}^k = A\left(\frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j}; dx^k\right). \quad (12.8)$$

The components are functions of x in a chart. Thus we can write this tensor field as

$$A = A_{ij}^k dx^i \otimes dx^j \otimes \frac{\partial}{\partial x^k}, \quad (12.9)$$

where the \otimes indicates a ‘product’, in the sense that its action on two vectors and a 1-form is a product of the respective components,

$$\left(dx^i \otimes dx^j \otimes \frac{\partial}{\partial x^k}\right)(u, v; \omega) = u^i v^j \omega_k. \quad (12.10)$$

Thus we find, in agreement with the earlier definition,

$$A(u, v; \omega) = A_{ij}^k u^i v^j \omega_k. \quad (12.11)$$

Under a change of charts, i.e. coordinate system $x^i \rightarrow x'^{i'}$, the components of the tensor field change according to

$$A = A_{ij}^k dx^i \otimes dx^j \otimes \frac{\partial}{\partial x^k} = A_{i'j'}^{k'} dx'^{i'} \otimes dx'^{j'} \otimes \frac{\partial}{\partial x'^{k'}} \quad (12.12)$$

Since

$$dx'^{i'} = \frac{\partial x'^{i'}}{\partial x^i} dx^i, \quad \frac{\partial}{\partial x'^{i'}} = \frac{\partial x^i}{\partial x'^{i'}} \frac{\partial}{\partial x^i} \quad (12.13)$$

(i and i' are not equal in general), we get

$$A_{ij}^k dx^i \otimes dx^j \otimes \frac{\partial}{\partial x^k} = A_{i'j'}^{k'} \frac{\partial x'^{i'}}{\partial x^i} dx^i \otimes \frac{\partial x'^{j'}}{\partial x^j} dx^j \otimes \frac{\partial x^k}{\partial x'^{k'}} \frac{\partial}{\partial x^k}. \quad (12.14)$$

Equating components, we can write

$$A_{ij}^k = A_{i'j'}^{k'} \frac{\partial x'^{i'}}{\partial x^i} \frac{\partial x'^{j'}}{\partial x^j} \frac{\partial x^k}{\partial x'^{k'}} \quad (12.15)$$

$$A_{i'j'}^{k'} = A_{ij}^k \frac{\partial x^i}{\partial x'^{i'}} \frac{\partial x^j}{\partial x'^{j'}} \frac{\partial x'^{k'}}{\partial x^k}. \quad (12.16)$$

From now on, we will use the notation ∂_i for $\frac{\partial}{\partial x^i}$ and $\partial_i f$ for $\frac{\partial f}{\partial x^i}$ unless there is a possibility of confusion. This will save some space and make the formulae more readable.

We can calculate the Lie derivative of a tensor field (with respect to a vector field u , say) by using the fact that \mathcal{L}_u is a derivative on the modules of vector fields and 1-forms, and by assuming Leibniz rule for tensor products. Consider a tensor field

$$T = T_{a \dots b}^{m \dots n} \partial_m \otimes \dots \otimes \partial_n \otimes dx^a \otimes \dots \otimes dx^b. \quad (12.17)$$

Then

$$\begin{aligned} \mathcal{L}_u T &= (\mathcal{L}_u T_{a \dots b}^{m \dots n}) \partial_m \otimes \dots \otimes \partial_n \otimes dx^a \otimes \dots \otimes dx^b \\ &\quad + T_{a \dots b}^{m \dots n} (\mathcal{L}_u \partial_m) \otimes \dots \otimes \partial_n \otimes dx^a \otimes \dots \otimes dx^b + \dots \\ &\quad + T_{a \dots b}^{m \dots n} \partial_m \otimes \dots \otimes \partial_n \otimes (\mathcal{L}_u dx^a) \otimes \dots \otimes dx^b, + \dots \end{aligned} \quad (12.18)$$

where the dots stand for the terms involving all the remaining upper and lower indices. Since the components of a tensor field are functions on the manifold, we have

$$\mathcal{L}_u T_{a \dots b}^{m \dots n} = u^i \partial_i T_{a \dots b}^{m \dots n}, \quad (12.19)$$

and we also know that

$$\mathcal{L}_u \partial_m = -\frac{\partial u^i}{\partial x^m} \partial_i, \quad \mathcal{L}_u dx^a = \frac{\partial u^a}{\partial x^i} dx^i. \quad (12.20)$$

Putting these into the expression for the Lie derivative for T and relabeling the dummy indices, we find the components of the Lie derivative,

$$\begin{aligned} (\mathcal{L}_u T)_{a \dots b}^{m \dots n} &= u^i \partial_i T_{a \dots b}^{m \dots n} \\ &\quad - T_{a \dots b}^{i \dots n} \partial_i u^m - \dots - T_{a \dots b}^{m \dots i} \partial_i u^n \\ &\quad + T_{i \dots b}^{m \dots n} \partial_a u^i + \dots + T_{a \dots i}^{m \dots n} \partial_b u^i. \end{aligned} \quad (12.21)$$