## Chapter 16

## Metric tensor

• A metric on a vector space V is a function  $g: V \times V \to \mathbb{R}$  which is

*i*) bilinear:

$$g(av_1 + v_2, w) = ag(v_1, w) + g(v_2, w)$$
  

$$g(v, w_1 + aw_2) = g(v, w_1) + ag(v, w_2), \quad (16.1)$$

i.e., g is a (0,2) tensor;

*ii*) symmetric:

$$g(v,w) = g(w,v);$$
 (16.2)

*iii*) non-degenerate:

$$g(v,w) = 0 \qquad \forall w \qquad \Rightarrow v = 0.$$
 (16.3)

• If for some  $v, w \neq 0$ , we find that g(v, w) = 0, we say that v, w are **orthogonal**.

• Given a metric g on V, we can always find an **orthonormal basis**  $\{e_{\mu}\}$  such that  $g(e_{\mu}, e_{\nu}) = 0$  if  $\mu \neq \nu$  and  $\pm 1$  if  $\mu = \nu$ .

• If the number of (+1)'s is p and the number of (-1)'s is q, we say that the metric has **signature** (p,q).

We have defined a metric for a vector space. We can generalize this definition to a manifold  $\mathcal{M}$  by the following.

• A metric g on a manifold  $\mathcal{M}$  is a (0, 2) tensor field such that if (v, w) are smooth vector fields, g(v, w) is a smooth function on  $\mathcal{M}$ , and has the properties (16.1), (16.2) and (16.3) mentioned earlier.  $\Box$ 

It is possible to show that smoothness implies that the signature is constant on any connected component of  $\mathcal{M}$ , and we will assume that it is constant on all of  $\mathcal{M}$ .

A vector space becomes related to its dual space by the metric. Given a vector space V with metric g, and vector v defines a linear map  $g(v, \cdot) : V \to \mathbb{R}$ ,  $w \mapsto g(v, w) \in \mathbb{R}$ . Thus  $g(v, \cdot) \in V^*$  where  $V^*$ is the dual space of V. But  $g(v, \cdot)$  is itself linear in v, so the map  $V \to V^*$  defined by  $g(v, \cdot)$  is linear. Since g is non-degenerate, this map is an isomorphism. It then follows that on a manifold we can use the metric to define a linear isomorphism between vectors and 1-forms.

In a basis, the components of the metric are  $g_{\mu\nu} = g(e_{\mu}, e_{\nu})$ . This is an  $n \times n$  matrix in an *n*-dimensional manifold. We can thus write  $g(v, w) = g_{\mu\nu}v^{\mu}w^{\nu}$  in terms of the components. Non-degeneracy implies that this matrix is invertible. Let  $g^{\mu\nu}$  denote the inverse matrix. Then, by definition of an inverse matrix, we have

$$g_{\mu\nu}g^{\nu\lambda} = \delta^{\lambda}_{\mu} = g^{\lambda\nu}g_{\mu\nu} \,. \tag{16.4}$$

Then the linear isomorphism takes the following form.

i) If  $v = v^{\mu}e_{\mu}$  is a vector field in a chart, and  $\{\lambda^{\mu}\}$  is the dual basis to  $\{e_{\mu}\}$ ,

$$g(v,\cdot) = v_{\mu}\lambda^{\mu}, \qquad (16.5)$$

where  $v_{\mu} = g_{\mu\nu}v^{\nu}$ .

*ii*) If  $A = A_{\mu}\lambda^{\mu}$  is a 1-form written in a basis  $\{\lambda^{\mu}\}$ , the corresponding vector field is  $A^{\mu}e_{\mu}$ , where  $A^{\mu} = g^{\mu\nu}A_{\nu}$ .

This is the isomorphism between vector fields and 1-forms. (We could of course define a similar isomorphism between vectors and covectors without referring to a manifold.) A similar isomorphism holds for tensors, e.g. in terms of components,

$$T^{\mu\nu} \longleftrightarrow T^{\mu}_{\ \nu} \longleftrightarrow T^{\mu}_{\mu} \longleftrightarrow T_{\mu\nu} \tag{16.6}$$

$$T^{\mu\nu\rho\cdots} \longleftrightarrow T^{\mu\nu}{}_{\rho}{}^{\cdots} \longleftrightarrow T^{\mu\nu}{}_{\rho\cdots} \longleftrightarrow T_{\mu\nu\rho}{}^{\cdots} \longleftrightarrow \cdots \quad (16.7)$$

These correspondences are not equalities — the components are not equal. What it means is that, if we know one set of components, say  $T^{\mu\nu\rho\cdots}$ , and the metric, we also know every other set of components.

• Using the fact that a non-degenerate metric defines a 1-1 linear map between vectors and 1-forms, we can define an **inner product** of 1-forms, by

$$\langle A \mid B \rangle = g^{\mu\nu} A_{\mu} B_{\nu} \tag{16.8}$$

for 1-forms A, B. This result is independent of the choice of basis, i.e. independent of the coordinate system, just like the **inner product** of vector fields,

$$\langle v | w \rangle = g(v, w) = g_{\mu\nu} v^{\mu} w^{\nu}$$
. (16.9)

Given a manifold with metric, there is a canonical volume form dV (sometimes written as vol), which in a coordinate chart reads

$$dV = \sqrt{|\det g_{\mu\nu}|} dx^1 \wedge \dots \wedge dx^n \,. \tag{16.10}$$

Note that despite the notation, this is not a 1-form, nor the gradient of some function V. This is clearly a volume form because it is an n-form which is non-zero everywhere, as  $g_{\mu\nu}$  is non-degenerate.

We need to show that this definition is independent of the chart. Take an overlapping chart. Then in the new chart, the corresponding volume form is

$$dV' = \sqrt{|\det g'_{\mu\nu}|} dx'^1 \wedge \dots \wedge dx'^n \,. \tag{16.11}$$

We wish to show that dV' = dV. In the overlap,

$$dx^{\prime\mu} = \frac{\partial x^{\prime\mu}}{\partial x^{\nu}} dx^{\nu} = A^{\mu}_{\nu} dx^{\nu} \,(\text{say}) \tag{16.12}$$

Then  $dx'^1 \wedge \cdots \wedge dx'^n = (\det A) dx^1 \wedge \cdots \wedge dx^n$ .

On the other hand, if we look at the components of the metric tensor in the new chart,

$$g'_{\mu\nu} = g(\partial'_{\mu}, \partial'_{\nu})$$

$$= \left(\frac{\partial x^{\alpha}}{\partial x'^{\mu}} \partial_{\alpha}, \frac{\partial x^{\beta}}{\partial x'^{\nu}} \partial_{\beta}\right)$$

$$= g\left(\left(A^{-1}\right)^{\alpha}_{\mu} \partial_{\alpha}, \left(A^{-1}\right)^{\beta}_{\nu} \partial_{\beta}\right)$$

$$= \left(A^{-1}\right)^{\alpha}_{\mu} \left(A^{-1}\right)^{\beta}_{\nu} g_{\alpha\beta}.$$
(16.13)

Taking determinants, we find

$$\det g'_{\mu\nu} = (\det A)^{-2} (\det g_{\mu\nu}) . \qquad (16.14)$$

Thus

$$\sqrt{|\det g'_{\mu\nu}|} = |\det A|^{-1} \sqrt{|\det g_{\mu\nu}|}, \qquad (16.15)$$

and so dV' = dV.

• This is called the **metric volume form** and written as

$$dV = \sqrt{|g|} dx^1 \wedge \dots \wedge dx^n \tag{16.16}$$

in a chart.

When we write dV, sometimes we mean the *n*-form as defined above, and sometimes we mean  $\sqrt{|g|}d^nx$ , the measure for the usual integral. Another way of writing the volume form in a chart is in terms of its components,

$$dV = \frac{\sqrt{|g|}}{n!} \epsilon_{\mu_1 \cdots \mu_n} dx^{\mu_1} \wedge \cdots \wedge dx^{\mu_n}$$
(16.17)

where  $\epsilon$  is the totally antisymmetric Levi-Civita symbol, with  $\epsilon_{12\cdots n} = +1$ . Thus  $\sqrt{|g|} \epsilon_{\mu_1\cdots\mu_n}$  are the components of the volume form.